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EP66

FREQUENCY INVERTER

0.4kW - 90kW / 0.5HP - 120HP
cUL/UL Certification valid for 0.4kW-15kW / 0.5HP-20HP



EP66

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FREQUENCY INVERTER

HIGHLIGHTS

DSP based high-tech motor control concept, suitable for V/Hz, SENSORLESS VECTOR, PMM synchronous motor control, SPEED/TORQUE control mode

Intelligent AUTOTUNING functions for quick and easy set-up

Rugged construction, IP66/NEMA 4X

Flexible configurable 4 line character display – MODBUS-RS485 ready. CANbus for master/slave mode

Removable cable conduit plate, including vent with humidity barrier

Space inside the drive for customer options like, main/emergency switch, start / stop selectors, potentiometer and brake resistor

Optional built-in brake chopper

C3 class filter standard – optional C1 EMC filter build in for 1. Environment (residential area)

Universal parameter set for all kind of industrial applications, including integrated PID controller routines, automatic carrier frequency and V/Hz curve adjustment for advanced torque control

Eura DV software for inverter control, programming and troubleshooting Parameter duplication stick including USB to RS-485 converter

Approved and certified for worldwide standards, by an independent organization



Naming Rule

Model naming rule

EP66 - 0007 T3 I1

Mark	Structure Code			
	I1~I6			
Mark	Input Power Type			
	S2	1-phase 220~240VAC		
	T2	3-phase 220~240VAC		
T3	3-phase 380~480VAC			
Motor power				
Mark	0007	0015	0022
Motor power(kW)	0.75	1.5	2.2
Product series: EP66				

Function naming rule

U5 F15 AD01 B1 R3

Filter	R3	EMC C3 level filter	Note 1
Braking mode	B1	Dynamic braking	Note 2
Keypad type	AD01	Segment LCD	Note 3
Communication	F15	Modbus terminal block	Note 4
Certificate type	U5	UL+cUL+CE	Note 4

Note 1: R3: EMC C3 level, test condition: power cable is 25m shielded wire.

Note 2: Dynamic braking: The inverter model for S2 and T2 is optional; The inverter model for T3:

Standard ($\leq 15\text{kW}$); Optional ($\geq 18.5\text{kW}$)

Note 3: EP66 supports 2 kinds of keypad type, user can select as needed;

Keypad code	Keypad definition
AD01	AD English 1-line LCD keypad without potentiometer
AD02	AD English 4-line LCD keypad without potentiometer

Note 4: Certification And Communication Type

Structure Code	Certificate	Certificate code	Communication	Communication code
I1~I3	U5	UL+cUL+CE	F2	Modbus
	U1	CE	F15	CAN communication (free protocol) +Modbus
I4~I6	U1	CE	F15	CAN communication (free protocol) +Modbus

Technical Specifications

	Items	Contents
Input	Rated Voltage Range	T3 380V-480V +10%/-15%; S2/T2 220V-240V ±15%
	Rated Frequency	50/60Hz
Output	Rated Voltage Range	3-phase 0-Input
	Frequency Range	0.50~650.0Hz
Control Mode	Carrier Frequency	800~16000Hz; Fixed carrier-wave and random carrier-wave can be selected by F159.
	Input Frequency Resolution	Digital setting: 0.01Hz; Analog setting: Max frequency 0.1%
	Control Mode	Sensorless Vector Control (open-loop vector control) V/F control, PMSM sensorless vector control
	Start Torque	0.5Hz / 150% (SVC), 5% of rated speed / 100% of rated torque (PMSM)
	Speed-Control Scope	1:100 (SVC), 1:20 (PMSM)
	Steady Speed Precision	±0.5% (SVC)
	Torque Control Precision	±5% (SVC)
	Overload Capacity	150% rated current, 60 seconds. Adjustable as required
	Torque Elevating	Auto torque promotion, For advanced torque control, manual torque promotion includes 1-20 curves
	V/F Curve	3 kinds of modes: beeline type, square type and under-defined V/F curve.
	Startup Mode	Direct startup, speed track startup (V/F control)
	DC Braking	DC braking frequency: 0.2~50.00Hz, braking time: 0.00~30.00s
	Jogging Control	Jogging frequency range: Min frequency~Max frequency, Jogging acceleration/ deceleration time: 0.1~30.00s
	Auto Circulating Running And Multi-Stage Speed Running	Auto circulating running or terminals control can realize 15-stage speed running.
Built-In PID Adjusting	Easy to realize a system for process closed-loop control	
Auto Voltage Regulation (AVR)	When the source voltage changes, the modulation rate will be adjusted automatically, resulting in an unchanged output voltage	
Operation	Frequency Setting	Potentiometer or external analog signal (0~5V, 0~10V, 0~20mA); keypad (terminal)▲ / ▼ keys, external control logic and automatic circulation setting.
	Start/Stop Control	Terminal control, keypad control or communication control.
	Running Command Channels	3 kinds of channels from keypad panel, control terminal and MODBUS.
Function	Frequency Source	Frequency sources: given digit, given analog voltage, given analog current and given MODBUS
	Accessorial Frequency Source	6 kinds of accessorial frequency
Optional	Built-in EMI filter, Built-in braking unit, Modbus, Keypad panel	
Protection Function	Input phase loss, Output phase loss, input under-voltage, DC over-voltage, over-current, inverter over-load, motor over-load, current stall, over-heat, external disturbance, under-load, pressure control, analog line disconnected, oPEn fault, STO function.	
Display	Output frequency, rotate-speed (rpm/min), output current, output voltage, DC bus voltage, PID feedback value, PID setting value, linear-velocity, types of faults, and parameters for the system and operation; LED indicators showing the current working status of inverter.	
Environment Conditions	Equipment Location	In harsh conditions, prevent dust of other thing from entering inverter totally. Completely protected against jets of water and heavy waves. Meeting EN 60529 standard.
	Environment Temperature	-10℃ ~ +40℃

Items	Contents	
Environment Conditions	Vibration Strength	Below 0.5g (acceleration)
	Height Above Sea Level	1000m or below (derating use if higher than 1000m)
Protection Level	IP66/NEMA 4X	
Class Of Pollution	PD2	
Applicable Motor	0.4~90kW	

Functions of Control Terminals

Terminal	Type	Description	Function
DO1	Output Signal	Multifunctional output terminal 1	When token function enabled, the value between this terminal and CM is 0V,24V when disabled; The max output frequency is 100kHz when high-frequency output; DO1 is high frequency output and it is not recommended to use intermediate relay.
DO2		Multifunctional output terminal 2	When the token function is valid, the value between this terminal and CM is 0V; when disabled, the value is 24V.
TA		Relay contact	TC is a common point, TB-TC are normally closed contacts, TA-TC are normally open contacts. The contact capacity of 15kW and below 15kW inverter is 10A/125VAC, N0/NC 3A or 250VAC/30VDC.
TB			
TC			
AO1 ^{note1}	Analog Output	Running frequency	It is connected with frequency meter, speedometer or ammeter externally, and its minus pole is connected with GND. See F423~F426 for details.
AO2 ^{note1}		Current display	It is connected with ammeter externally, and its minus pole is connected with GND. See F427~F430 for details.
10V	Analog Power Supply	Self contained power supply	Internal 10V self-contained power supply. When used externally, it can only be used as the power supply for voltage control signals with restricted current below 20mA.
AI1 ^{note2}	Input Signal	Voltage analog input port	When analog speed control is adopted, the voltage signal is inputted through this terminal. The range of voltage input is 0~10V, grounding: GND. When potentiometer speed control is adopted, this terminal is connected with center tap, earth wire to be connected to GND.
AI2 ^{note2}		Voltage / Current analog input port	When analog speed control is adopted, the voltage or current signal is input through this terminal. The range of voltage input is 0~5V or 0~10V and the current input is 0~20mA, the the input resistor is 500Ohm, and grounding: GND. If the input is 4~20mA, it can be realized through adjusting parameter F406. The voltage or current signal can be chosen by coding switch. See table 4-2 for details, the current channel (0-20mA) is chosen before deliver.
24V	Power Supply	Control power supply	Power: 24±1.5V, grounding is CM; current is restricted below 50mA for external use.
CM	Common Port	Grounding of control power supply	The grounding of 24V power supply and other control signals.
DI1	Digital Input Control Terminal	Jogging terminal	When this terminal is valid, the inverter will have jogging running. The jogging function of this terminal is valid under both at stopped and running status. This terminal can also be used as high-speed pulse input port. The max frequency is 50K.
DI2		External emergency stop	When this terminal is valid, "ESP" malfunction signal will be displayed.
DI3		"FWD" Terminal	When this terminal is valid, inverter will run forward.
DI4		"REV" Terminal	When this terminal is valid, inverter will run reversely.
DI5		Reset terminal	Make this terminal valid under fault status to reset the inverter.
DI6		Free-stop	Make this terminal valid during running can realize free stop.
DI7 ^{note3}		Running terminal	When this terminal is in the valid state, inverter will run by the acceleration time.
DI8 ^{note3}		Stop terminal	Make this terminal valid during running can realize stop by the deceleration time.

The functions of output terminals shall be defined per manufacturer's value. Their initial state may be changed through changing function codes.

The functions of input terminals shall be defined per manufacturer's value. Other functions can also be defined by changing function codes.

Terminal	Type	Description	Function
GND	Analog Grounding	Self-contained power supply ground	Ground terminal of external control signal (voltage control signal or current source control signal) is also the ground of 10V power supply of this inverter.
+5V	Power	Self-contained power	Grounding for digital signal
A+	485 Communication Terminals	Positive polarity of differential signal	Standard: TIA/EIA-485 (RS-485) Communication protocol: Modbus Communication rate: 1200/2400/4800/9600/19200/38400/57600bps
B-		Negative polarity of differential signal	

Note:

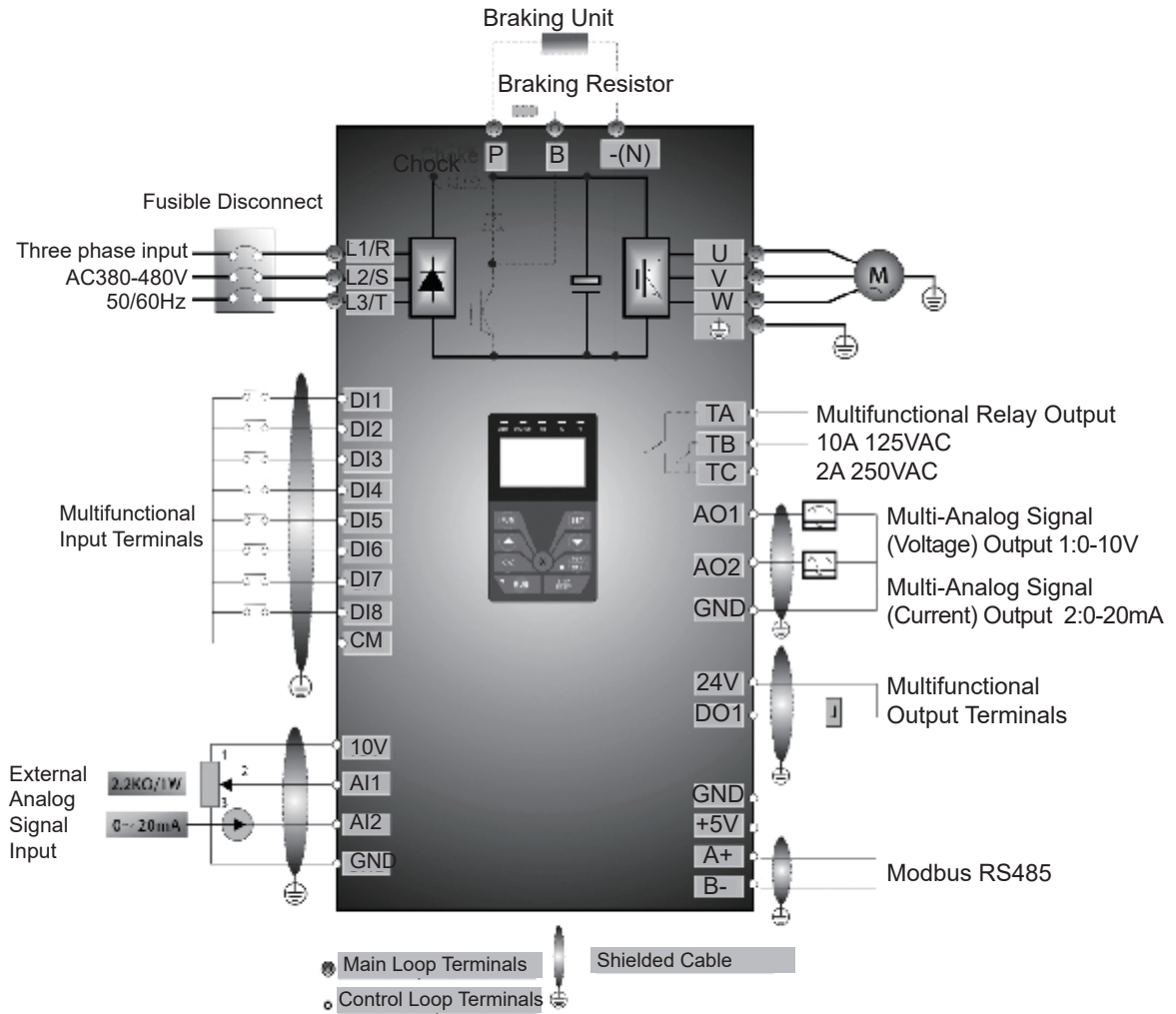
- 1.AO1 can output voltage and current signal, and AI2 can only output current.
- 2.AI1 can only accept voltage signal, AI2 can only accept voltage signal and current signal.
- 3.15kW and below have no DO2,AO2,DI7 and DI8 terminals.

TA	TB	TC	DO1	24V	CM	DI1	DI2	DI3	DI4	DI5	DI6	10V	AI1	AI2	GND	AO1				
TA	TB	TC	DO1	DO2	24V	CM	DI1	DI2	DI3	DI4	DI5	DI6	DI7	DI8	+10V	AI1	AI2	GND	AO1	AO2
GND	+5V	A+	B-																	

Product List

Model	Rated current	Remote Keypad	Structure code	Weight (kg)	Dimensions (W×H×D-mm)	Cooling mode	Remarks
EP66-0004S2	0.4kW-2.5A-0.3HP		I1	6.2	200×412×198	Self cooling	1-phase 220V plastic hanging
EP66-0007S2	0.75kW-4.5A-1HP		I1	6.2	200×412×198	Self cooling	
EP66-0015S2	1.5kW-7A-2HP		I1	6.2	200×412×198	Self cooling	
EP66-0022S2	2.2kW-10A-3HP		I1	6.2	200×412×198	Air cooling	
EP66-0004T2	0.4kW-2.5A-0.5HP		I1	6.2	200×412×198	Self cooling	3-phase 220V plastic hanging
EP66-0007T2	0.75kW-4.5A-1HP		I1	6.2	200×412×198	Self cooling	
EP66-0015T2	1.5kW-7A-2HP		I1	6.2	200×412×198	Self cooling	
EP66-0022T2	2.2kW-10A-3HP		I1	6.2	200×412×198	Air cooling	
EP66-0004T3	0.4kW-1.2A-0.5HP	AD01 Or AD02	I1	6.2	200×412×198	Self cooling	3-phase 380V plastic hanging
EP66-0007T3	0.75kW-2A-1HP		I1	6.2	200×412×198	Self cooling	
EP66-0015T3	1.5kW-4A-2HP		I1	6.2	200×412×198	Self cooling	
EP66-0022T3	2.2kW-6.5A-3HP		I1	6.2	200×412×198	Air cooling	
EP66-0030T3	3.0kW-7A-4HP		I1	6.2	200×412×198	Air cooling	
EP66-0040T3	4.0kW-9A-5.5HP		I1	6.2	200×412×198	Air cooling	
EP66-0055T3	5.5kW-12A-7.5HP		I2	8.2	242×418×198	Air cooling	
EP66-0075T3	7.5kW-17A-10HP		I2	8.2	242×418×198	Air cooling	
EP66-0110T3	11kW-23A-15HP		I3	11.3	242×471×228	Air cooling	
EP66-0150T3	15kW-32A-20HP		I3	11.3	242×471×228	Air cooling	
EP66-0185T3	18.5kW-38A-25HP	I4	25	242×650×325	Air cooling	3-phase 380V metal hanging	
EP66-0220T3	22kW-44A-30HP	I4	25	242×650×325	Air cooling		
EP66-0300T3	30kW-60A-40HP	I4	25	242×650×325	Air cooling		
EP66-0037T3	37kW-75A-50HP	I5	40	308×680×379	Air cooling		
EP66-0450T3	45kW-90A-60HP	I5	40	308×680×379	Air cooling		
EP66-0550T3	55kW-110A-75HP	I5	40	308×680×379	Air cooling		
EP66-0750T3	75kW-150A-100HP	I6	57	370×770×404	Air cooling		
EP66-0900T3	90kW-180A-120HP	I6	57	370×770×404	Air cooling		

Wiring Diagram



Basic Wiring Diagram For Three-phase AC Drives (NPN type)

Note:

1. Connect power terminals L1 and L2 with power grid for single-phase inverters.
2. Remote-control panels are connected with 8 core telephone wire. 485 communication port is on the control terminals
3. 485 communication port has built-in standard MODBUS communication protocol. The terminal sequence is GND, +5V, A+, B-.
4. Inverter($\leq 15\text{kW}$) has 6 multifunctional input terminals DI1~DI6.
5. The contact capacity of inverter is 10A/125VAC, NO/NC: 3A 250VAC/30VDC.

EURA DRIVES CANADA LTD

328 Consumers Road

North York, Ontario M2J 1P8

Canada

Te : +1 647 512 7958

contact@euradrives.net

www.euradrives.net

